Accredited entity according to ČSN EN ISO/IEC 17025:2018:

TÜV SÜD Czech s.r.o.

CAB number 2405, Calibration Laboratory Novodvorská 994, 142 21 Praha 4

Calibration laboratory locations:

1. UNO TECHNOLOGY PARK Bezděčín, Hala H1a, č.p. 108, 293 01 Mladá Boleslav, Czech Republic

CMC for the field of measured quantity: Length

Ord. num- ber ¹	Calibrated quantity / Subject of calibration		Nomina	l range		Parameter(s) of	Lowest stated expanded measurement	Calibration principle	Calibration procedure	Location
		min. ı	unit	max.	unit	the measurand	uncertainty ²	Canoration principle	identification ³	Location
1*	Sensors of displacement,							comparison with	I540 - 068 - 10	
	distance and position	0 mm	to	300	mm		0.04 mm	a height gauge		
		300 mm	to	1,500	mm		0.20 mm			
2	Belt motion sensors							comparison with a	I540 - 068 - 10	
		-400 mm	to	400	mm		$(0.2 \cdot L + 0.40) \text{ mm}$	calibration jig		

¹ Asterisk at the ordinal number identifies the calibrations, which the Laboratory is qualified to carry out outside the permanent laboratory premises.

² The expanded measurement uncertainty is in accordance with ILAC-P14 and EA-4/02 M a part of CMC, and it is the lowest value of the respective uncertainty. If not stated otherwise, its coverage probability is approx. 95 %. If not stated otherwise, the uncertainty values stated without a unit are relative to the measured value. The uncertainty value stated herein is based on the best conditions achievable by the laboratory; the uncertainty value of a specific calibration may be higher, depending on the conditions of such a calibration. For identical extreme values of adjacent ranges, the lower uncertainty value always applies.

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Explanatory notes:

L – measured length in metres

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CMC for the field of measured quantity: Plane angle

Ord. num-	Calibrated quantity / Subject of		Nom	inal range			Parameter(s) of the	. measurement	Calibration principle	Calibration procedure identification ³	Location
ber ¹	calibration	min.	unit	max	•	unit	measurand	uncertainty ²			Location
1*	Sensors of position and inclinometers								comparison with a digital inclinometer	I540 - 068 - 10	
		0 °)	to	360 °			0.02°	or rotary index table		

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CMC for the field of measured quantity: Mechanical motion

Ord. num-	Calibrated quantity / Subject of		Nomi	nal ra	ange		Parameter(s) of the	Lowest stated expanded measurement	Calibration	Calibration procedure	Loca-
ber ¹	calibration	min.	unit		max.	unit	measurand	uncertainty ²	principle	identification ³	tion
1*	Meters and sensors of half-sine wave mechanical shock								comparison with a standard	I 540 – 068 – 43	
	acceleration	100 r	$\mathbf{m} \cdot \mathbf{s}^{-2}$	to	1,471	$m \cdot s^{-2}$		1.0 %	acceleration sensor		
		1,471 r		to	2,000	$m \cdot s^{-2}$		1.5 %			
		2,000 r	$\mathbf{m} \cdot \mathbf{s}^{-2}$	to	40,000	$m \cdot s^{-2}$		1.8 %			
2	Acceleration of linear mechanical vibrations of harmonic wave form ^{4 5} / Vibration sensors, vibrometers, vibration calibrators, vibration								comparison with a standard acceleration sensor	I 540 – 068 – 45	
	generators ^{4 5}	0.1	m⋅s ⁻²	to	295 m	• s ⁻²	5 Hz up to 10 Hz	2.0 %			
							10 Hz up to 20 Hz	1.0 %			
							20 Hz up to 80 Hz	0.75 %			
							80 Hz	0.5 %			
							80 Hz up to 1,000 Hz	0.75 %			
							1,000 Hz up to 5,000 Hz	1.0 %			
							5,000 Hz up to 10,000 Hz	2.0 %			
3	Sensitivity of vibration sensors and vibrometers ⁴⁵								comparison with a vibration	I 540 – 068 – 45	
			$mV/(m \cdot s^{-2})$	to	10,000 m	$V/(m \cdot s^{-2})$	5 Hz up to 10 Hz	2.0 %	standard		
		0.01 p	$pC/(m \cdot s^{-2})$	to	1,000 pC	$C/(m \cdot s^{-2})$	10 Hz up to 20 Hz	1.0 %			
		0.01 r	$mV/(m \cdot s^{-1})$	to	10,000 m	$V/(m \cdot s^{-1})$	20 Hz up to 80 Hz	0.75 %			
		0.01 r	mV/m	to	10,000 m	V/m	80 Hz	0.5 %			
							80 Hz up to 1,000 Hz	0.75 %			
							1,000 Hz up to 5,000 Hz	1.0 %			
							5,000 Hz up to 10,000 Hz	2.0 %			

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Ord. num-	Calibrated quantity / Subject of		Non	ninal ra	nge		Parameter(s) of the	Lowest stated expanded measurement	Calibration	Calibration procedure	Loca-
ber ¹	calibration	min.	unit		max.	unit	measurand	uncertainty ²	principle	identification ³	tion
4	Transmission of amplifiers,	0.001			10.000			0.5.%	direct measurement	I 540 – 068 – 45	
	filters and vibrometers	0.001	mV/pC	to	10,000	mV/pC	0.2 Hz up to 1 Hz	0.5 %			
							1 Hz up to 5,000 Hz	0.4 %			
							5,000 Hz up to 10,000 Hz	0.4 %			
							10,000 Hz up to 20,000 Hz	0.6 %			
							20,000 Hz up to 50,000 Hz	1.0 %			
		0.001	V/V	to	1,000	V/V	0.2 Hz up to 1 Hz	0.4 %			
							1 Hz up to 20,000 Hz	0.3 %			
							20,000 Hz up to 50,000 Hz	1.0 %			
5	Vibration measurement ⁴⁵ /	0.1	-2	4.5	205	_2	5 H	2.0.%	direct measurement	I 540 – 068 – 45	
	Vibration generators	0.1	m⋅s ⁻²	to	295	$m \cdot s^{-2}$	5 Hz up to 10 Hz	2.0 %			
							10 Hz up to 20 Hz	1.0 %			
							20 Hz up to 80 Hz	0.75 %			
							80 Hz	0.5 %			
							80 Hz up to 1,000 Hz	0.75 %			
							1,000 Hz up to 5,000 Hz	1.0 %			
							5,000 Hz up to 10,000 Hz	2.0 %			
6*	Speedometers, GPS and radar speedometers, speed sensors								comparison with distance and time	I 540 – 068 – 29	
			km∙h ⁻¹ km∙h ⁻¹			km·h ⁻¹ km·h ⁻¹	distance standard measured distance	0.02 % 0.04 %	standard		
7*		20	K111' 11		150	K111, 11		0.04 /0	1	1540 060 05	
7*	Speedometers with a rolling wheel								direct generation of circumferential	I 540 – 068 – 05	
		2	m∙min ⁻¹		1	00 m·min ⁻¹		$0.1 \% + 0.01 \text{ m} \cdot \text{min}^{-1}$	velocity		

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Ord. num-	Calibrated quantity / Subject of calibration		Non	ninal rang	ge		Parameter(s) of the measurand	Lowest stated expanded measurement	Calibration	Calibration procedure	Loca-
ber ¹		min.	unit		max.	unit		uncertainty ²	principle	identification ³	tion
8*	Revolution counters, rpm								direct measurement	I 540 – 068 – 05	
	sensors, stroboscopes								of an optical or		
		500	min ⁻¹	to	10,000) min ⁻¹		0.006 min ⁻¹	electrical signal		
		10,000	min ⁻¹	to	100,000) min ⁻¹		0.06 min ⁻¹			

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⁴ The measured quantity can also be velocity and displacement, assuming that a vibrational signal of the harmonic waveform is generated at a known frequency.

⁵ It can also be given in the units g, pC/g or mV/g, where 1 g = 9.807 m s⁻²

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CMC for the field of measured quantity: Pressure, mechanical stress

Ord. num-	Calibrated quantity / Subject of calibration		ľ	Nominal r	ange		Parameter(s) of the	Lowest stated expanded measurement	Calibration	Calibration procedure	Location
ber ¹		min.	unit		max.	unit	measurand	uncertainty ²	principle	identification ³	Location
1	Deformation and electromechanical manometers	0.5	1.D		0		gas	0.115	comparison with a digital pressure gauge	I540 – 068 – 3 (ČSN EN 837– 1, ČSN EN 837– 3,	
		-95 0	kPa MPa	to to	0.7	kPa MPa	gas/ liquid	0.1 kPa 0.03 % + 0.08 kPa	-	EURAMET cg-17)	
		0.7	MPa	to	3.5	MPa		0.03 % + 0.4 kPa 0.03 % + 0.8 kPa			
		3.5 7	MPa MPa	to to	7 20	MPa MPa		0.03% + 0.8 K a 0.03% + 2.3 kPa			
							oil	3.5 kPa	comparison with a piston pressure		
		0 6	MPa MPa	to to	6 60	MPa MPa		0.06 %	gauge		

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CMC for the field of measured quantity: Time, frequency

Ord. num-	Calibrated quantity / Subject of		Nominal r	ange		Parameter(s) of	Lowest stated expanded measurement	Calibration principle	Calibration procedure	Location
ber ¹	calibration	min.	unit	max.	unit	the measurand	uncertainty ²		identification ³	Location
1*	Digital speed cameras							direct measurement with a standard	I 540 – 068 – 44	
				1,000) Hz		2.1·10 ⁻⁴ Hz	counter		
2*	Time interval / stopwatches, timers and other							comparison with a standard counter	I 540 – 068 – 02	
	chronometers	1 ms 1 s	to to	1,000 10,800) ms) s		1.0·10 ⁻⁵ s 6.0·10 ⁻⁴ s			

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