EHSQ CONSULTING, s.r.o. CAB number 2364, Calibration Laboratory Blatec 48, 783 75 Blatec

CMC for the field of measured quantity: Length

Ord. number	Calibrated quantity / Subject of	Nom	inal	range	Parameter(s) of the	Lowest stated expanded measurement	Calibration principle	Calibration procedure	Work-
1	1 calibration			max unit	measurand	uncertainty ²		identification ³	place
1	Setting and check rings	3 mm	to	6 mm		$(9 \cdot L + 3.0) \mu m$	Measurement on a length gauge	KPD01KN	
		6 mm	to	300 mm		$(10 \cdot L + 0.8) \mu m$			
2	Parallel gauge blocks	0.5 mm	to	100 mm		$(5{\cdot}L+0.2)\mu m$	Measurement on a parallel gauge block comparator	KPD02MK	
3	Cylindrical and slot gauges, measuring cylinders and setting						Measurement on a length gauge	KPD03KV	
	gauges	0 mm	to	600 mm		$(9 \cdot L + 0.7) \mu m$			
4	Snap gauges	3 mm	to	6 mm		$(10 \cdot L + 3.0) \mu m$	Measurement on a length gauge or a profile projector	KPD04KT	
		6 mm	to	300 mm		$(15 \cdot L + 0.8) \mu m$			
5	Feeler gauges	0 mm		10 mm		0.7 µm	Measurement on a length gauge	KPD05SL	
6	Thread gauges						Measurement on a length gauge	KPD06KZ	
	male gauge	0 mm	to	300 mm		$(10 \cdot L + 2.6) \mu m$			
	ring	3 mm	to	300 mm		$(10 \cdot L + 3.1) \mu m$			
7	Thread-measuring wires	0.17 mm	to	6.35 mm		0.5 µm	Measurement on a length gauge	KPD07DZ	
8	Slide gauges	0 mm	to	2000 mm		$(20 \cdot L + 20) \mu m$	Measurement by parallel gauge blocks	KPD11MP	
9	Micrometers	0 mm	to	1,000 mm		$(14 \cdot L + 1.3) \mu m$	Measurement by parallel gauge blocks	KPD12MT	
10	Dial indicators							KPD13UC	
	direct, lever	0 mm	to	100 mm		$(16 \cdot L + 0.8) \mu m$	Measurement on a length gauge		
	with arms	0 mm	to	200 mm		$(17 \cdot L + 3.0) \mu m$	Measurement by setting rings and parallel gauge blocks		
11	Mechanical sliding depth gauges	0 mm	to	600 mm		$(15 \cdot L + 12) \mu m$	Measurement by parallel gauge blocks	KPD14HP	
12*	Mechanical height gauges	0 mm	to	1,000 mm		$(15 \cdot L + 1.4) \mu m$	Measurement by parallel gauge blocks	KPD15VP	
13	Inside micrometer gauges	0 mm	to	1,000 mm		$(15 \cdot L + 1.4) \mu m$	Measurement on a length gauge	KPD16OM	
14	Internal gauges							KPD17DT	
	two-contact	0 mm	to	600 mm		$(15 \cdot L + 1.4) \mu m$	Measurement on a length gauge		
	three-contact	3 mm	to	200 mm		$(17 \cdot L + 2.0) \mu m$	Measurement by setting rings		

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Ord. number	Calibrated quantity / Subject of	Non	ninal	range		Parameter(s)	Lowest stated expanded measurement	Calibration principle	Calibration procedure	Work-
1	1 calibration			max	unit	measurand	uncertainty ²	Cumpration principle	identification ³	place
15	Pasameters	0 mm	to	300	mm		$(8 \cdot L + 0.8) \mu m$	Measurement by parallel gauge blocks	KPD18PM	
16	Steel gauges - rigid, thin, flexible,							Comparison with a rigid steel gauge	KPD09OM	
	tape	0 mm	to	5,000	mm		0.15 mm			
17	Surface rules							Using parallel gauge blocks on a surface	KPD19PP	
		100 mm	to	1,000	mm		7 μm	plate		
		500 mm	to	2,000	mm		$(1.2 \cdot L + 5.2) \mu m$	Measurement with an electronic level		
18*	Surface plates	0 mm	to	3,000	mm		$(1.2 \cdot M + 5.2) \mu m$	Measurement by an electronic level	KPD20PD	
19	Thickness gauges								KPD21SV	
	surface layers	0 mm	to	2	mm		9.0 µm	Measurement using sheets		
	of wall thickness	0 mm	to	200	mm		$(14 \cdot L + 12) \mu m$	Using reference gauges		
20	Thread gauges, radius gauges,							Measurement on a profile projector	KPU34MP	
	gauges, measuring jigs and templates	0 mm	to	200	mm		$(20 \cdot L + 4.0) \mu m$			
21	Flat, trying and knife angles							Measurement of deviation from	KPU31UL	
								perpendicularity with a height gauge and		
		0 mm	to	630	mm		$(15 \cdot M + 6.0) \mu m$	dial gauge		
22*	Length gauges, profile projectors,								KPD10LI	
	microscopes, devices with a linear	_								
	measuring system	0 mm	to	3,000	mm		$(2 \cdot L + 0.2) \mu m$	Measurement by a laser interferometer		
		0 mm	to	300	mm		$(12 \cdot L + 2.0) \mu m$	Measurement with a reference gauge		
23	Roughness meters	0.1 µm	to	6.4	μm		$(8 \% + 0.20) \mu m$	Measurement by a roughness standard	KPD22DR	
24	Roughness standards	0.1 µm	to	6.4	μm		$(8 \% + 0.20) \mu m$	Measurement by a roughness meter	KPD22DR	

¹ Asterisk at the ordinal number identifies the calibrations, which the Laboratory is qualified to carry out outside the permanent laboratory premises.

² The expanded measurement uncertainty is in accordance with ILAC-P14 and EA-4/02 M a part of CMC and it is the lowest value of the respective uncertainty. If not stated otherwise, its coverage probability is approx. 95 %. If not stated otherwise, the uncertainty values stated without a unit are relative to the measured value. The uncertainty value stated herein is based on the best conditions achievable by the laboratory; the uncertainty value of a specific calibration may be higher depending on the conditions of such a calibration. For identical extreme values of adjacent ranges, the lower uncertainty value always applies.

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Explanatory notes:

L Calibrated length

M Calibrated area

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CMC for the field of measured quantity: Plane angle

Ord. number	Calibrated quantity / Subject of	Nom	inal r	ange	Parameter(s) of	Lowest stated expanded		Calibration	Work-
	calibration	min unit		max unit	the measurand	measurement uncertainty ²	Calibration principle	procedure identification ³	place
1	Plane angle meters	0 °	to	360 °		2	Using angle gauges and sine ruler	KPU32MU	
2	Levels								
	- Mechanical	0 mm/m	to	2 mm/m		$(3.5 \cdot \alpha + 5.2) \mu m/m$	Using an electronic level	KPU33LV	
	- Builder's	0 mm/m	0 mm/m to 2 mm/m			0.2 mm/m	Using a dial indicator		
3	Thread gauges, radius gauges, gauges, measuring jigs and templates	0 °	to	360 °		4′	Measurement on a profile projector	KPU34MP	
4*	Rotary angle sensors and torque tools						Comparison with a rotation angle	KPU32MU	
		0 °	to	360 °		0.2°	sensor		

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 $\alpha \quad \text{angle in mm/m}$

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CMC for the field of measured quantity: Mechanical motion

Ord.	Calibrated quantity / Subject of		Nomina	l range		Donomotor (a) of the	Lowest stated		Calibration	Work	
numb er ¹	calibration	min	unit	max	unit	measurand	measurement uncertainty ²	Calibration principle	procedure identification ³	place	
1*	Acceleration of linear harmonic							Measurement or	KPV01VZ		
	mechanical vibrations / vibration							comparison on a			
	calibrators, vibrometers, vibration	0.1 m.s	-2 to	500	m. s ⁻²	3 Hz to 10 kHz	1.0%	device			
	systems	0.1 11.5	i ii	500	111.2	5 112 to 10 KHZ	1 /0	By simulated electrical			
		1 mV	to	o 7	V	3 Hz to 10 kHz	1 %	signal			
2*	Frequency of mechanical linear							Measurement or	KPV01VZ		
	motion							comparison on a			
		2.11		10	1 7 7	0.1. 500 2	1.0/	standard calibration			
2*		3 Hz	to	b 10	kHz	$0.1 \text{ to } 500 \text{ m} \cdot \text{s}^{-2}$	1 %	device			
3*	vibration sine signal ^{4,5}							standard calibration	KPV01VZ		
	violation – sine signal					3 Hz to 10 kHz	1 %	device			
	- acceleration, 0.1 m·s ⁻² to 500 m·s ⁻²	0.01 pC	$/ \text{m} \cdot \text{s}^{-2}$ to	b 1.000	pC / $m \cdot s^{-2}$		_ , .				
		0.01 mV	$/ \text{m} \cdot \text{s}^{-2}$ to	b 10,000	$mV / m \cdot s^{-2}$						
	- velocity up to 0.4 m·s ⁻¹	0.01 pC	$/ \mathbf{m} \cdot \mathbf{s}^{-1}$ to	o 1,000	$pC / m \cdot s^{-1}$						
		0.01 mV	$1/\mathrm{m}\cdot\mathrm{s}^{-1}$ to	o 10,000	$mV / m \cdot s^{-1}$						
	– deviation up to 5mm	0.01 pC	/ mm to	o 1,000	pC / mm						
		0.01 mV	/ mm to	b 10,000	mV / mm						
4	Sensitivity of vibration sensors ⁵							Measurement on a	KPV01VZ		
						1 Hz to 5 kHz	15%	device			
	- angular acceleration up to 5.300 $^{\circ}$ s					1 112 to 5 KHZ	1.5 /0				
		0.01 mV	$/ \circ \cdot s^{-2}$ to	b 10,000	mV / °⋅s ⁻²						
	– angular velocity up to 2.5 · 10 ⁶ ° · s ⁻¹	0.01 mV	$/ \circ \cdot s^{-1}$ to	b 10,000	mV / °⋅s ⁻¹						
	– angular deviation up to 30 $^\circ$	0.01 mV	/° to	o 10,000	mV / °						

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Ord. numb er ¹	Calibrated quantity / Subject of		Nomi	nal ra	ange		Donomotor (g) of the	Lowest stated		Calibration	Work
	calibration	min	unit		max	unit	measurand	measurement uncertainty ²	Calibration principle	procedure identification ³	place
5	Sensitivity of vibration sensors ⁵ by mechanical shock – half-sine signal	0.01 j 0.01 i	$pC / m \cdot s^{-2}$ $mV / m \cdot s^{-2}$	to to	1,000 p 10,000 r	$pC / m \cdot s^{-2}$ $nV / m \cdot s^{-2}$	$50 \text{ m} \cdot \text{s}^{-2} \text{ to}$ $1 \cdot 10^5 \text{ m} \cdot \text{s}^{-2}$	1.5 %	Measurement on a standard calibration device	KPV01VZ	
6*	Rpm meters	6 1 6 s	min ⁻¹ s ⁻¹	to to	8,000 r 10 ⁵ s	nin ⁻¹ 5 ⁻¹		(0.2 + 1d) (0.001% + 1d)	Contact method Contactless method	KPV01VZ	

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⁴ Acceleration can be specified also in g, sensor sensitivity in pC/g, resp. mV/g units, where 1 g = 9.806 m.s^{-2}

⁵ The values for (angular) acceleration, velocity and deviation are equivalent and can be freely converted to each other.

Explanatory notes:

d Scale division of a calibrated meter

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CMC for the field of measured quantity: Force – moment of force

Ord.	Calibrated quantity / Subject of		Nomir	al range		Parameter(s)	Lowest stated		Calibration procedure	Work.
numbe r ¹	calibration	min u	nit	max	unit	of the measurand	measurement uncertainty ²	Calibration principle	identification ³	place
1	Torque wrenches and screwdrivers	0.02 Nn	n to	0 1,00	00 Nm		0.7 %	Comparison with a standard torque sensor	KPM41KM (ČSN EN ISO 6789-2)	
2	Torque sensors and calibration devices	0.01 Nn	n to) 1()0 Nm		0.2 %	Measurement by torque arms and weights	KPM42SM (ČSN EN ISO 6789-2)	
		20 Nn	n to	1,00	00 Nm		0.2 %	Comparison with reference torque wrenches		
3*	Tighteners and tightening devices	0.02 Nn	n to	50	00 Nm		1.2 %	Comparison with a standard torque sensor	KPM43UM	
4	Load cells, dynamometres	0 N	to	20	00 N	tension, pressure	0.1 % +1 mN	Measurement by standard weights	KPS01SL (ČSN EN ISO 376)	
5	Testing devices, presses, load							Measurement by standard dynamometer	KPS01SL	
	cells	0 N	to) 1	0 kN	tension, pressure	0.2 % + 0.01 N		(CSN EN ISO 376, ČSN EN ISO 7500-1)	

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